The problemThe variational formulationBlow up versus compactnessSome ideas of the proofComments and open problems000000000000000000000000000000

# Prescribing Gaussian curvature on compact surfaces and geodesic curvature on its boundary

#### David Ruiz

Joint work with R. López Soriano and A. Malchiodi

www.arxiv.org/1806.11533

Satellite conference on Nonlinear PDE, Fortaleza, July 2018.

The problemThe variational formulation000000000

Blow up versus com

Some ideas of the pro

Comments and open problems





- 2 The variational formulation
- Blow up versus compactness
- 4 Some ideas of the proof



# Prescribing Gaussian curvature under conformal changes of the metric

A classical problem in geometry is the prescription of the Gaussian curvature on a compact Riemannian surface  $\Sigma$  under a conformal change of the metric.

Denote by  $\tilde{g}$  the original metric and  $g = e^{u}\tilde{g}$ . The curvature then transforms according to the law:

$$-\Delta u + 2\tilde{K}(x) = 2K(x)e^{u},$$

where  $\Delta = \Delta_{\tilde{g}}$  is the Laplace-Beltrami operator and  $\tilde{K}$ , K stand for the Gaussian curvatures with respect to  $\tilde{g}$  and g, respectively.

The solvability of this equation has been studied for several decades: Berger, Kazdan and Warner, Moser, Aubin, Chang-Yang...



Let  $\Sigma$  be a compact surface with boundary. In this talk we consider the problem of prescribing the Gaussian curvature of  $\Sigma$  and the geodesic curvature of  $\partial \Sigma$  via a conformal change of the metric.



Let  $\Sigma$  be a compact surface with boundary. In this talk we consider the problem of prescribing the Gaussian curvature of  $\Sigma$  and the geodesic curvature of  $\partial \Sigma$  via a conformal change of the metric.

This question leads us to the boundary value problem:

$$\begin{cases} -\Delta u + 2\tilde{K}(x) = 2K(x)e^{u}, & x \in \Sigma, \\ \frac{\partial u}{\partial \nu} + 2\tilde{h}(x) = 2h(x)e^{u/2}, & x \in \partial\Sigma. \end{cases}$$

Here  $e^{u}$  is the conformal factor,  $\nu$  is the normal exterior vector and

- (1)  $\tilde{K}$ ,  $\tilde{h}$  are the original Gaussian and geodesic curvatures, and
- (2) K, h are the Gaussian and geodesic curvatures to be prescribed.



# Antecedents

 The higher order analogue: prescribing scalar curvature S on Σ and mean curvature H on ∂Σ.

The case S = 0 and H = const is the well-known Escobar problem: Ambrosetti-Li-Malchiodi, Escobar, Han-Li, Marques,...

- The case h = 0: Chang-Yang.
- The case K = 0: Chang-Liu, Liu-Huang...

The blow-up phenomenon has also been studied: Guo-Liu, Bao-Wang-Zhou, Da Lio-Martinazzi-Rivière...

• The case of constants *K*, *h*:

A parabolic flow converges to constant curvatures (Brendle).

Classification of solutions in the annulus (Jiménez).

Classification of solutions in the half-plane (Li-Zhu, Zhang, Gálvez-Mira).

Our aim is to consider the case of nonconstant K, h. The only results we are aware of are due to Cherrier, Hamza.



# **Preliminaries**

By the Gauss-Bonnet Theorem,

$$\int_{\Sigma} K e^{u} + \oint_{\partial \Sigma} h e^{u/2} = \int_{\Sigma} \tilde{K} + \oint_{\partial \Sigma} \tilde{h} = 2\pi \chi(\Sigma),$$

where  $\chi(\Sigma)$  is the Euler characteristic of  $\Sigma$ .



## Preliminaries

By the Gauss-Bonnet Theorem,

$$\int_{\Sigma} K e^{u} + \oint_{\partial \Sigma} h e^{u/2} = \int_{\Sigma} \tilde{K} + \oint_{\partial \Sigma} \tilde{h} = 2\pi \chi(\Sigma),$$

where  $\chi(\Sigma)$  is the Euler characteristic of  $\Sigma$ .

It is easy to show that we can prescribe  $h = 0, K = sgn(\chi(\Sigma))$ . Then:

$$\begin{cases} -\Delta u + 2\tilde{K} = 2K(x)e^{u}, & x \in \Sigma, \\ \frac{\partial u}{\partial \nu} = 2h(x)e^{u/2}, & x \in \partial\Sigma, \end{cases}$$

where  $\tilde{K} = sgn(\chi(\Sigma))$ .

We are interested in the case of negative *K*. For existence of solutions, we will focus on the case  $\chi \leq 0$ .

# The variational formulation

The associated energy functional is given by  $I: H^1(\Sigma) \to \mathbb{R}$ ,

$$I(u) = \int_{\Sigma} \left( \frac{1}{2} |\nabla u|^2 + 2\tilde{K}u + 2|K(x)|e^u \right) - 4 \oint_{\partial \Sigma} h e^{u/2}.$$

For the statement of our results it will be convenient to define the function  $\mathfrak{D}: \partial \Sigma \to \mathbb{R},$ 

$$\mathfrak{D}(x) = \frac{h(x)}{\sqrt{|K(x)|}}.$$

The function  $\mathfrak{D}$  is scale invariant.

# A trace inequality

## Proposition

For any  $\varepsilon > 0$  there exists C > 0 such that:

$$4\int_{\partial\Sigma}h(x)e^{u/2} \leq (\varepsilon + \max_{p\in\partial\Sigma}\mathfrak{D}^+(p))\left[\int_{\Sigma}\frac{1}{2}|\nabla u|^2 + 2|K(x)|e^u\right] + C.$$

In particular, if  $\mathfrak{D}(p) < 1 \forall p \in \partial \Sigma$ , then *I* is bounded from below.

## A trace inequality

#### Proposition

For any  $\varepsilon > 0$  there exists C > 0 such that:

$$4\int_{\partial\Sigma}h(x)e^{u/2} \leq (\varepsilon + \max_{p\in\partial\Sigma}\mathfrak{D}^+(p))\left[\int_{\Sigma}\frac{1}{2}|\nabla u|^2 + 2|K(x)|e^u\right] + C.$$

In particular, if  $\mathfrak{D}(p) < 1 \forall p \in \partial \Sigma$ , then *I* is bounded from below.

Assume that h > 0 is constant, and take N a vector field in  $\Sigma$  such that  $N(x) = \nu(x)$  on the boundary,  $|N(x)| \le 1$ . Then,

$$4 \int_{\partial \Sigma} h e^{u/2} = 4 \int_{\partial \Sigma} h e^{u/2} N(x) \cdot \nu(x)$$
$$= 4 \int_{\Sigma} h e^{u/2} \left[ div N + \frac{1}{2} \nabla u \cdot N \right] \leq C \int_{\Sigma} e^{u/2} + 2 \int_{\Sigma} h e^{u/2} |\nabla u|$$
$$\leq C \int_{\Sigma} e^{u/2} + 2 \int_{\Sigma} h^2 e^u + \frac{1}{2} \int_{\Sigma} |\nabla u|^2.$$

 The problem
 The variational formulation
 Blow up versus compactness
 Some ideas of the proof
 Comments and open problems

 0000
 00000
 00000
 00000
 0000
 0000

## The case $\chi(\Sigma) < 0$

#### Theorem

Assume that  $\chi(\Sigma) < 0$ . Let *K*, *h* be continuous functions such that K < 0 and  $\mathfrak{D}(p) < 1$  for all  $p \in \partial \Sigma$ . Then the functional *I* is coercive and attains its infimum.

By the trace inequality,

$$I(u) \ge \int_{\Sigma} \varepsilon |\nabla u|^2 + 2\varepsilon |K(x)|e^u + 2\tilde{K}u - C.$$

Since  $\tilde{K} < 0$ ,  $\lim_{u \to \pm \infty} 2\delta e^u + 2\tilde{K}u = +\infty$ , so *I* is coercive.

 The problem
 The variational formulation
 Blow up versus compactness
 Some ideas of the proof
 Comments and open problems

 0000
 00000
 00000
 00000
 0000
 0000

# The case $\chi(\Sigma) < 0$

#### Theorem

Assume that  $\chi(\Sigma) < 0$ . Let *K*, *h* be continuous functions such that K < 0 and  $\mathfrak{D}(p) < 1$  for all  $p \in \partial \Sigma$ . Then the functional *I* is coercive and attains its infimum.

By the trace inequality,

$$I(u) \ge \int_{\Sigma} \varepsilon |\nabla u|^2 + 2\varepsilon |K(x)|e^u + 2\tilde{K}u - C.$$

Since  $\tilde{K} < 0$ ,  $\lim_{u \to \pm \infty} 2\delta e^u + 2\tilde{K}u = +\infty$ , so *I* is coercive.

If  $\chi(\Sigma) = \tilde{K} = 0$ , *I* is bounded from below but not coercive! The reason is that  $\int_{\Sigma} u_n$  could go to  $-\infty$  for a minimizing sequence  $u_n$ .

# Minimizers for $\chi(\Sigma) = 0$ .

#### Theorem

Assume that  $\chi(\Sigma) = 0$ . Let *K*, *h* be continuous functions such that K < 0 and:

(1)  $\mathfrak{D}(p) < 1$  for all  $p \in \partial \Sigma$ . 

Then I attains its infimum.

Observe that if  $u_n = -n$ , then:  $I(u_n) = \int_{\Sigma} 2|K(x)|e^{-n} - 4 \oint_{\partial \Sigma} he^{-n/2} \nearrow 0$ .

# Minimizers for $\chi(\Sigma) = 0$ .

#### Theorem

Assume that  $\chi(\Sigma) = 0$ . Let *K*, *h* be continuous functions such that K < 0 and:

(1)  $\mathfrak{D}(p) < 1$  for all  $p \in \partial \Sigma$ .  $(2) \oint_{\partial \Sigma} h > 0.$ Then I attains its infimum.

Observe that if  $u_n = -n$ , then:  $I(u_n) = \int_{\Sigma} 2|K(x)|e^{-n} - 4 \oint_{\partial \Sigma} he^{-n/2} \nearrow 0$ .



The problem The variational formulation Blow up versus compactness Some ideas of the proof Comments and open problems

# Min-max for $\chi(\Sigma) = 0$ .

### Theorem

Assume that  $\chi(\Sigma) = 0$ . Let *K*, *h* be continuous functions such that K < 0 and:

**1** 
$$\mathfrak{D}(p) > 1$$
 for some  $p \in \partial \Sigma$ .

Then I has a mountain-pass geometry.



# Blow-up versus compactness

Here the (PS) condition is not known to hold. By using the monotonicity trick of Struwe, we can obtain solutions of perturbed problems.

The guestion of compactness or blow-up for this kind of problems has attracted a lot of attention since the works of Brezis-Merle, Li-Shafrir, etc.

# Blow-up versus compactness

Here the (PS) condition is not known to hold. By using the monotonicity trick of Struwe, we can obtain solutions of perturbed problems.

The guestion of compactness or blow-up for this kind of problems has attracted a lot of attention since the works of Brezis-Merle, Li-Shafrir, etc.

Let  $u_n$  be a blowing-up sequence (namely,  $\sup\{u_n(x)\} \to +\infty$ ) of solutions to the problem:

$$\begin{cases} -\Delta u_n + 2\tilde{K}_n(x) = 2K_n(x)e^{u_n}, & \text{in } \Sigma, \\ \frac{\partial u_n}{\partial \nu} + 2\tilde{h}_n(x) = 2h_n(x)e^{u_n/2}, & \text{on } \partial \Sigma. \end{cases}$$
(1)

Here  $\tilde{K}_n \to \tilde{K}, \tilde{h}_n \to \tilde{h}, K_n \to K, h_n \to h$  in  $C^1$  sense, with K < 0. By integrating:

$$\int_{\Sigma} K_n e^{u_n} + \oint_{\partial \Sigma} h_n e^{u_n/2} = \int_{\Sigma} K_n + \oint_{\partial \Sigma} h_n \to \chi_0 = 2\pi \chi(\Sigma).$$

Hence there could be compensation of diverging masses!!



# A blow-up analysis

#### Theorem

Assume that  $u_n$  is unbounded from above and define its singular set:

$$S = \{ p \in \Sigma : \exists x_n \to p \text{ such that } u_n(x_n) \to +\infty \}.$$
(2)

The problem The variational formulation Blow up versus compactness Some ideas of the proof Comments and open problems

00000

# A blow-up analysis

#### Theorem

Assume that  $u_n$  is unbounded from above and define its singular set:

$$S = \{ p \in \Sigma : \exists x_n \to p \text{ such that } u_n(x_n) \to +\infty \}.$$
(2)



# The infinite mass case

3 If  $\int_{\Sigma} e^{u_n}$  is unbounded, there exists a unit positive measure  $\sigma$  on  $\Sigma$  such that:

a) 
$$\frac{|K_n|e^{u_n}}{\int_{\Sigma} |K_n|e^{u_n}} \rightharpoonup \sigma, \quad \frac{h_n e^{u_n/2}}{\oint_{\partial \Sigma} h_n e^{u_n/2}} \rightharpoonup \sigma|_{\partial \Sigma}.$$
  
b)  $supp \ \sigma \subset \{p \in \partial \Sigma : \ \mathfrak{D}(p) \ge 1, \ \mathfrak{D}_{\tau}(p) = 0\}.$ 

# The infinite mass case

3 If  $\int_{\Sigma} e^{u_n}$  is unbounded, there exists a unit positive measure  $\sigma$  on  $\Sigma$  such that:

a) 
$$\frac{|K_n|e^{u_n}}{\int_{\Sigma} |K_n|e^{u_n}} \rightharpoonup \sigma, \quad \frac{h_n e^{u_n/2}}{\oint_{\partial \Sigma} h_n e^{u_n/2}} \rightharpoonup \sigma|_{\partial \Sigma}.$$
  
b)  $supp \ \sigma \subset \{p \in \partial \Sigma : \ \mathfrak{D}(p) \ge 1, \ \mathfrak{D}_{\tau}(p) = 0\}$ 

If there exists  $m \in \mathbb{N}$  such that  $ind(u_n) \leq m$  for all n, then  $S = S_0 \cup S_1$ , where:

$$S_0 \subset \{p \in \partial \Sigma : \mathfrak{D}(p) = 1, \mathfrak{D}_{\tau}(p) = 0\},$$
  
 $S_1 = \{p_1, \dots p_k\} \subset \{\mathfrak{D}(p) > 1 \text{ and } \Phi(p) = 0\}, \ k \leq m.$   
If moreover  $\chi_0 \leq 0$ , then  $S_1$  is empty.

# Back to the case $\chi(\Sigma) = 0$ .

### Theorem

Assume that  $\chi(\Sigma) = 0$ . Let *K*, *h* be  $C^1$  functions such that K < 0 and:

- **1**  $\mathfrak{D}(p) > 1$  for some  $p \in \partial \Sigma$ .

# Back to the case $\chi(\Sigma) = 0$ .

## Theorem

Assume that  $\chi(\Sigma) = 0$ . Let *K*, *h* be  $C^1$  functions such that K < 0 and:

**1** 
$$\mathfrak{D}(p) > 1$$
 for some  $p \in \partial \Sigma$ .

3 
$$\mathfrak{D}_{\tau}(p) \neq 0$$
 for any  $p \in \partial \Sigma$  with  $\mathfrak{D}(p) = 1$ .

Then I has a mountain-pass critical point.

We obtain solutions of perturbed problems of mountain-pass type, hence they have Morse index at most 1 ([Fang-Ghoussoub, 94, 99]).

Those solutions cannot blow-up so that they converge to a true solution of our problem.

# Obstructions to existence

# Proposition (Jiménez 2012)

If  $\Sigma$  is an cylinder and K = -1,  $h_1$  and  $h_2$  are constants, then our problem is solvable iff

- (1)  $h_1 + h_2 > 0$  and both  $h_i < 1$  (minima).
- 2  $h_1 + h_2 < 0$  and some  $h_i > 1$  (mountain-pass).
- **3**  $h_1 = 1, h_2 = -1$  or viceversa.

# Obstructions to existence

## Proposition (Jiménez 2012)

If  $\Sigma$  is an cylinder and K = -1,  $h_1$  and  $h_2$  are constants, then our problem is solvable iff

- (1)  $h_1 + h_2 > 0$  and both  $h_i < 1$  (minima).
- 2  $h_1 + h_2 < 0$  and some  $h_i > 1$  (mountain-pass).
- **3**  $h_1 = 1, h_2 = -1$  or viceversa.

#### Proposition

Let  $\Sigma$  be a compact surface with boundary, and assume that  $h(p) > \sqrt{|K^-(q)|}$  for all  $p \in \partial \Sigma$ ,  $q \in \Sigma$ . Then  $\Sigma$  is homeomorphic to a disk.

•000000000

The problem The variational formulation Blow up versus compactness Some ideas of the proof Comments and open problems

# A classification result in the half-plane

### Theorem (Gálvez-Mira 2009)

Let *u* be a solution of:

$$\begin{cases} -\Delta u = 2K_0 e^u & \text{in } \mathbb{R}^2_+, \\ \frac{\partial u}{\partial \nu} = 2h_0 e^{u/2} & \text{in } \partial \mathbb{R}^2_+, \end{cases} \implies \begin{cases} -\Delta u = -2e^u & \text{in } \mathbb{R}^2_+, \\ \frac{\partial u}{\partial \nu} = 2\mathfrak{D}_0 e^{u/2} & \text{in } \partial \mathbb{R}^2_+. \end{cases}$$

with  $\mathfrak{D}_0 = \frac{h_0}{\sqrt{|K_0|}}$ . Then the following holds:

The problem The variational formulation Blow up versus compactness Some ideas of the proof Comments and open problems

# A classification result in the half-plane

### Theorem (Gálvez-Mira 2009)

Let u be a solution of:

$$\begin{cases} -\Delta u = 2K_0 e^u & \text{in } \mathbb{R}^2_+, \\ \frac{\partial u}{\partial \nu} = 2h_0 e^{u/2} & \text{in } \partial \mathbb{R}^2_+, \end{cases} \implies \begin{cases} -\Delta u = -2e^u & \text{in } \mathbb{R}^2_+, \\ \frac{\partial u}{\partial \nu} = 2\mathfrak{D}_0 e^{u/2} & \text{in } \partial \mathbb{R}^2_+. \end{cases}$$

with  $\mathfrak{D}_0 = \frac{h_0}{\sqrt{|K_0|}}$ . Then the following holds:

- If  $\mathfrak{D}_0 < 1$  there is no solution.
- If  $\mathfrak{D}_0 = 1$  the only solutions are:

$$u(s,t) = 2\log\left(\frac{\lambda}{1+\lambda t}\right), \ \lambda > 0, \ s \in \mathbb{R}, \ t \ge 0.$$

The problem The variational formulation Blow up versus compactness Some ideas of the proof Comments and open problems

# A classification result in the half-plane

• If  $\mathfrak{D}_0 > 1$ , then:

$$u(z) = 2\log\Big(\frac{2|g'(z)|}{1-|g(z)|^2},\Big),\,$$

where g is locally injective holomorphic map from  $\mathbb{R}^2_+$  to a disk of geodesic curvature  $\mathfrak{D}_0$  in the Poincaré disk  $\mathbb{H}^2$ . For instance, to B(0, R)with  $\mathfrak{D}_0 = \frac{1+R^2}{2R}$ .

The problem The variational formulation Blow up versus compactness Some ideas of the proof Comments and open problems

# A classification result in the half-plane

• If  $\mathfrak{D}_0 > 1$ . then:

$$u(z) = 2 \log \left( \frac{2|g'(z)|}{1 - |g(z)|^2}, \right),$$

where g is locally injective holomorphic map from  $\mathbb{R}^2_+$  to a disk of geodesic curvature  $\mathfrak{D}_0$  in the Poincaré disk  $\mathbb{H}^2$ . For instance, to B(0, R)with  $\mathfrak{D}_0 = \frac{1+R^2}{2R}$ .

#### Moreover, g is a Möbius transform if and only if

$$\textit{either } \int_{\mathbb{R}^2_+} e^u < +\infty \textit{ and } / \textit{ or } \oint_{\partial \mathbb{R}^2_+} e^{u/2} < +\infty.$$

In such case *u* can be written as:

$$u(s,t) = 2\log\left(\frac{2\lambda}{(s-s_0)^2 + (t+t_0)^2 - \lambda^2}\right), t \ge 0,$$

where  $\lambda > 0$ ,  $s_0 \in \mathbb{R}$ ,  $t_0 = \mathfrak{D}_0 \lambda$ . We call these solutions "bubbles".

# Passing to a limit problem in the half-plane

Let us recall the definition of the singular set:

$$S = \{p \in \Sigma : \exists y_n \in \Sigma, y_n \to p, u_n(y_n) \to +\infty\}.$$

### Proposition

Let  $p \in S$ . Then there exist  $x_n \in \Sigma$ ,  $x_n \to p$  such that, after a suitable rescaling, we obtain a solution of the problem in the half-plane in the limit.

In particular  $S \subset \{p \in \partial \Sigma : \mathfrak{D}(p) \geq 1\}$ .

In the Lioville equation, if the mass is finite, then a key integral estimate ([Brezis-Merle, 1991]) implies that S is finite. Hence one can take  $x_n$  as local maxima ([Li-Shafrir, 1994]).

Here the idea is to choose a **good sequence**  $x_n$ , even if they are not local maxima!

Let us fix  $p \in S$ . Via a conformal map we can pass to either  $B_0(r)$  or  $B_0^+(r)$ . By definition there exist  $y_n \in \Sigma$  with  $y_n \to p$  and  $u_n(y_n) \to +\infty$ . Define:

$$\varphi_n = e^{-\frac{u_n}{2}}, \ \varepsilon_n = e^{-\frac{u_n(y_n)}{2}} \to 0.$$

The problem The variational formulation Blow up versus compactness Some ideas of the proof Comments and open problems

The problem The variational formulation Blow up versus compactness Some ideas of the proof Comments and open problems

# Choosing good sequences

Let us fix  $p \in S$ . Via a conformal map we can pass to either  $B_0(r)$  or  $B_0^+(r)$ . By definition there exist  $y_n \in \Sigma$  with  $y_n \to p$  and  $u_n(y_n) \to +\infty$ . Define:

$$\varphi_n = e^{-\frac{u_n}{2}}, \ \varepsilon_n = e^{-\frac{u_n(y_n)}{2}} \to 0.$$

By Ekeland variational principle there exists a sequence  $x_n$  such that

• 
$$e^{-\frac{u_n(x_n)}{2}} \le e^{-\frac{u_n(y_n)}{2}}$$
,  
•  $|x_n - y_n| \le \sqrt{\varepsilon_n}$ ,  
•  $e^{-\frac{u_n(x_n)}{2}} \le e^{-\frac{u_n(z)}{2}} + \sqrt{\varepsilon_n} |x_n - z|$  for every  $z \in B$ .

The last conditions implies that, when we rescale, the rescaled functions are bounded from above, so we can pass to a limit.

The problem The variational formulation Blow up versus compactness Some ideas of the proof Comments and open problems

# Choosing good sequences

Let us fix  $p \in S$ . Via a conformal map we can pass to either  $B_0(r)$  or  $B_0^+(r)$ . By definition there exist  $y_n \in \Sigma$  with  $y_n \to p$  and  $u_n(y_n) \to +\infty$ . Define:

$$\varphi_n = e^{-\frac{u_n}{2}}, \ \varepsilon_n = e^{-\frac{u_n(y_n)}{2}} \to 0.$$

By Ekeland variational principle there exists a sequence  $x_n$  such that

• 
$$e^{-\frac{u_n(x_n)}{2}} \le e^{-\frac{u_n(y_n)}{2}}$$
,  
•  $|x_n - y_n| \le \sqrt{\varepsilon_n}$ ,  
•  $e^{-\frac{u_n(x_n)}{2}} \le e^{-\frac{u_n(z)}{2}} + \sqrt{\varepsilon_n} |x_n - z|$  for every  $z \in B$ .

The last conditions implies that, when we rescale, the rescaled functions are bounded from above, so we can pass to a limit.

- Since K(p) < 0, there is no entire solution of  $-\Delta u = 2K(p)e^u$  in  $\mathbb{R}^2$ .
- Hence p in  $\partial \Sigma$ , the limit problem is posed in a half-plane and  $\mathfrak{D}(p) > 1$ .

## Infinite mass

#### Proposition

Assume that  $\rho_n = \int_{\Sigma} |K_n| e^{u_n} \to +\infty$ ,  $\oint_{\partial \Sigma} |h| e^{u_n/2} \to +\infty$ . Then there exists a positive unit measure  $\sigma$  on  $\partial \Sigma$  such that:

$$\frac{|K_n|e^{u_n}}{\rho_n} \rightharpoonup \sigma, \ \frac{h_n e^{u_n/2}}{\rho_n} \rightharpoonup \sigma.$$

Multiplying the equation by  $\phi \in C^2(\Sigma)$  and integrating:

$$2\oint_{\partial\Sigma}h_ne^{u_n/2}\phi-2\int_{\Sigma}|K_n|e^{u_n}\phi=O(1)+\underbrace{\int_{\Sigma}u_n\Delta\phi+\oint_{\partial\Sigma}\frac{\partial\phi}{\partial\nu}u_n}_{o(\rho_n)}.$$

We use a Kato-type inequality to estimate  $u_n^-$ .

The variational formulation Blow up versus compactness Some ideas of the proof Comments and open problems

# On the support of $\sigma$

Clearly supp  $\sigma \subset S \subset \{p \in \partial \Sigma : \mathfrak{D}(p) \geq 1\}$ . Moreover, we have:

## Proposition

The support of  $\sigma$  is contained in the set  $\{p \in \partial \Sigma : \mathfrak{D}_{\tau}(p) = 0\}$ .

Let  $\Lambda_0$  be a connected component of  $\partial \Sigma$ . Via a conformal map, we can pass to a problem in an annulus.





Multiply the equation by  $\nabla u_n \cdot F$ , where *F* is a tangential vector field, to obtain:

$$\oint_{\Lambda_0} (4h_n e^{u_n/2} - 4\tilde{h}_n) (\nabla u_n \cdot F)$$

$$=\int_{\Sigma} \left[4\tilde{K}_n \nabla u_n \cdot F + 4e^{u_n} (\nabla K_n \cdot F + K_n \nabla \cdot F) + 2\underbrace{DF(\nabla u_n, \nabla u_n) - \nabla \cdot F |\nabla u_n|^2}_{22}\right].$$

Multiply the equation by  $\nabla u_n \cdot F$ , where *F* is a tangential vector field, to obtain:

$$\oint_{\Lambda_0} (4h_n e^{u_n/2} - 4\tilde{h}_n) (\nabla u_n \cdot F)$$

$$= \int_{\Sigma} [4\tilde{K}_n \nabla u_n \cdot F + 4e^{u_n} (\nabla K_n \cdot F + K_n \nabla \cdot F) + 2\underbrace{DF(\nabla u_n, \nabla u_n) - \nabla \cdot F |\nabla u_n|^2}_{??}].$$

We get rid of the Dirichlet term by using holomorphic functions F. Integrating by parts and passing to the limit, we obtain:

$$\oint_{\Lambda_0} \frac{\mathfrak{D}_{\tau}}{\mathfrak{D}} f \, d\sigma = 0,$$

where  $f = (F \cdot \tau)$ . But f can be any arbitrary analytic function, and then  $\mathfrak{D}_{\tau}\sigma = 0$  as a measure.



## Morse index

This is all the information that we can obtain without further assumptions on  $u_n$ .

From now on we assume that the sequence of solutions  $u_n$  has bounded Morse index.

If  $u_n$  has bounded Morse index, the solutions of the limit problem obtained by rescaling have finite Morse index.

# Morse index of the limit problem

#### Theorem

Let *u* be a solution of the problem:

$$\begin{cases} -\Delta u = -2e^{u} & \text{in } \mathbb{R}^{2}_{+}, \\ \frac{\partial u}{\partial \nu} = 2\mathfrak{D}_{0}e^{u/2} & \text{in } \partial \mathbb{R}^{2}_{+}. \end{cases}$$
(3)

Define:

$$\begin{split} \mathcal{Q}(\psi) &= \int_{\mathbb{R}^2_+} |\nabla \psi|^2 + 2 \int_{\mathbb{R}^2_+} e^u \psi^2 - \mathfrak{D}_0 \int_{\partial \mathbb{R}^2_+} e^{u/2} \psi^2, \text{ and} \\ &ind(v) = \sup\{ dim(E): \ E \subset C_0^\infty(\mathbb{R}^2_+) \text{ vector space}, \ \mathcal{Q}(\psi) < 0 \ \forall \ \psi \in E \}. \end{split}$$

# Morse index of the limit problem

#### Theorem

Let *u* be a solution of the problem:

<

$$\begin{cases} -\Delta u = -2e^{u} & \text{in } \mathbb{R}^{2}_{+}, \\ \frac{\partial u}{\partial \nu} = 2\mathfrak{D}_{0}e^{u/2} & \text{in } \partial \mathbb{R}^{2}_{+}. \end{cases}$$
(3)

Define:

$$\begin{split} \mathcal{Q}(\psi) &= \int_{\mathbb{R}^2_+} |\nabla \psi|^2 + 2 \int_{\mathbb{R}^2_+} e^u \psi^2 - \mathfrak{D}_0 \int_{\partial \mathbb{R}^2_+} e^{u/2} \psi^2, \text{ and} \\ &\text{ind}(v) = \sup\{ \dim(E): \ E \subset C_0^\infty(\mathbb{R}^2_+) \text{ vector space}, \ \mathcal{Q}(\psi) < 0 \ \forall \ \psi \in E \}. \end{split}$$

1 If  $\mathfrak{D}_0 = 1$ , then ind(u) = 0, that is, u is stable. 2 If  $\mathfrak{D}_0 > 1$  and u is a bubble, then ind(u) = 1. Otherwise,  $ind(u) = +\infty$ .

This theorem implies that infinite mass blow-up with bounded Morse index occurs only if  $\mathfrak{D}(p) = 1$ , and the number of bubbles is limited.

# Morse index of the limit problem

If  $\mathfrak{D}_0 = 1$ ,  $\psi(s, t) = \frac{1}{1+t}$  is a positive solution of the linearization.

If  $\mathfrak{D}_0 = 1$ ,  $\psi(s, t) = \frac{1}{1+t}$  is a positive solution of the linearization.

If  $\mathfrak{D}_0 > 1$ , then we pass to the problem posed in  $B(0, R) \subset \mathbb{H}^2$ :

$$\begin{cases} -\Delta \gamma + 2\gamma = 0, & \text{in } B(0, R), \\ \frac{\partial \gamma}{\partial \nu} = \lambda \gamma, & \text{in } \partial B(0, R). \end{cases}$$
(4)

• The functions 
$$\gamma_i(z) = \frac{z_i}{1-|z|^2}$$
 solve (4) with  $\lambda = \mathfrak{D}_0$ .

If  $\mathfrak{D}_0 = 1$ ,  $\psi(s, t) = \frac{1}{1+t}$  is a positive solution of the linearization.

If  $\mathfrak{D}_0 > 1$ , then we pass to the problem posed in  $B(0, R) \subset \mathbb{H}^2$ :

$$\begin{cases} -\Delta \gamma + 2\gamma = 0, & \text{in } B(0, R), \\ \frac{\partial \gamma}{\partial \nu} = \lambda \gamma, & \text{in } \partial B(0, R). \end{cases}$$
(4)

- The functions  $\gamma_i(z) = \frac{z_i}{1-|z|^2}$  solve (4) with  $\lambda = \mathfrak{D}_0$ .
- The function  $\gamma(z) = \frac{1+|z|^2}{1-|z|^2}$  solves (4) with  $\lambda = \frac{1}{\mathfrak{D}_0}$ .

If  $\mathfrak{D}_0 = 1$ ,  $\psi(s, t) = \frac{1}{1+t}$  is a positive solution of the linearization.

If  $\mathfrak{D}_0 > 1$ , then we pass to the problem posed in  $B(0, R) \subset \mathbb{H}^2$ :

$$\begin{cases} -\Delta \gamma + 2\gamma = 0, & \text{in } B(0, R), \\ \frac{\partial \gamma}{\partial \nu} = \lambda \gamma, & \text{in } \partial B(0, R). \end{cases}$$

(4)

- The functions  $\gamma_i(z) = \frac{z_i}{1-|z|^2}$  solve (4) with  $\lambda = \mathfrak{D}_0$ .
- The function  $\gamma(z) = \frac{1+|z|^2}{1-|z|^2}$  solves (4) with  $\lambda = \frac{1}{\mathfrak{D}_0}$ .
- For a convenient cut-off  $\phi$ ,  $\psi = \phi(g \circ \gamma)$  satisfies  $Q(\psi) < 0$ .

If  $\mathfrak{D}_0 = 1$ ,  $\psi(s, t) = \frac{1}{1+t}$  is a positive solution of the linearization.

If  $\mathfrak{D}_0 > 1$ , then we pass to the problem posed in  $B(0, R) \subset \mathbb{H}^2$ :

$$\begin{pmatrix} -\Delta\gamma + 2\gamma = 0, & \text{in } B(0, R), \\ \frac{\partial\gamma}{\partial\nu} = \lambda\gamma, & \text{in } \partial B(0, R). \end{cases}$$
(4)

- The functions  $\gamma_i(z) = \frac{z_i}{1-|z|^2}$  solve (4) with  $\lambda = \mathfrak{D}_0$ .
- The function  $\gamma(z) = \frac{1+|z|^2}{1-|z|^2}$  solves (4) with  $\lambda = \frac{1}{\mathfrak{D}_0}$ .
- For a convenient cut-off  $\phi$ ,  $\psi = \phi(g \circ \gamma)$  satisfies  $Q(\psi) < 0$ .
- If moreover  $\oint_{\partial \mathbb{R}^2_+} e^{u/2} = +\infty$  we can choose  $\phi$  to be 0 outside any arbitrary compact set.

# Explicit examples of blow-up

Let us consider the problem:

$$\left\{ \begin{array}{ll} -\Delta u = -2e^{u}, & \text{ in } A(0;r,1), \\ \frac{\partial u}{\partial \nu} + 2 = 2h_1 e^{u/2}, & \text{ on } |x| = 1, \\ \frac{\partial u}{\partial \nu} - \frac{2}{r} = 2h_2 e^{u/2}, & \text{ on } |x| = r. \end{array} \right.$$

Here K = -1 and h is constant on each component of the boundary. All solutions of this problem have been classified ([Jiménez, 2012]).

•••••

# Explicit examples of blow-up

Let us consider the problem:

<

$$\begin{cases} -\Delta u = -2e^u, & \text{in } A(0; r, 1), \\ \frac{\partial u}{\partial \nu} + 2 = 2h_1 e^{u/2}, & \text{on } |x| = 1, \\ \frac{\partial u}{\partial \nu} - \frac{2}{r} = 2h_2 e^{u/2}, & \text{on } |x| = r. \end{cases}$$

Here K = -1 and h is constant on each component of the boundary. All solutions of this problem have been classified ([Jiménez, 2012]).

For example, the function:

$$u(x) = \log\left(\frac{4}{|x|^2(\lambda + 2\log|x|)^2}\right), \quad \text{ for any } \lambda < 0,$$

is a solution with  $h_1 = 1$  and  $h_2 = -1$ . Observe that if  $\lambda$  tends to 0 then u blows up at a whole component of the boundary.

The singular set  $S = \{|x| = 1\}$  is not finite.



## A second example

Given any  $h_1 > 1$ ,  $\gamma \in \mathbb{N}$ , there exists a explicit solution:

$$u_{\gamma}(z) = 2 \log \left( \frac{\gamma |z|^{\gamma-1}}{h_1 + Re(z^{\gamma})} \right),$$

where  $h_2 = -h_1 r^{-\gamma}$ .

## A second example

Given any  $h_1 > 1$ ,  $\gamma \in \mathbb{N}$ , there exists a explicit solution:

$$u_{\gamma}(z) = 2 \log \left( \frac{\gamma |z|^{\gamma-1}}{h_1 + Re(z^{\gamma})} \right),$$

where  $h_2 = -h_1 r^{-\gamma}$ .

Those solutions blow up as  $\gamma \to +\infty$ , keeping  $h_1 > 1$  fixed. Also here  $S = \{|z| = 1\}$  but now  $h_1 > 1$ .

## A second example

Given any  $h_1 > 1$ ,  $\gamma \in \mathbb{N}$ , there exists a explicit solution:

$$u_{\gamma}(z) = 2 \log \left( \frac{\gamma |z|^{\gamma-1}}{h_1 + Re(z^{\gamma})} \right),$$

where  $h_2 = -h_1 r^{-\gamma}$ .

Those solutions blow up as  $\gamma \to +\infty$ , keeping  $h_1 > 1$  fixed. Also here  $S = \{|z| = 1\}$  but now  $h_1 > 1$ .

The asymptotic profile is:

$$u(s,t) = 2\log\left(\frac{e^{-t}}{h_1 + e^{-t}\cos s}\right),\,$$

defined in the half-plane  $\{t \ge 0\}$ . This is indeed a solution to the limit problem in the half-space with K = -1 and  $h_1 > 1$ , with infinite Morse index.



# **Open problems**



The necessity or not of the Morse index bound assumption.



- The necessity or not of the Morse index bound assumption.
- Existence of blowing-up solutions in non-constant curvature cases. Nonlocal effects are expected!



- The necessity or not of the Morse index bound assumption.
- Existence of blowing-up solutions in non-constant curvature cases. Nonlocal effects are expected!
- The case of the disk. Can we have coexistence of finite-mass and infinite-mass blow-up?



- The necessity or not of the Morse index bound assumption.
- Existence of blowing-up solutions in non-constant curvature cases. Nonlocal effects are expected!
- The case of the disk. Can we have coexistence of finite-mass and infinite-mass blow-up?
- Sign-changing curvatures.



- The necessity or not of the Morse index bound assumption.
- Existence of blowing-up solutions in non-constant curvature cases. Nonlocal effects are expected!
- The case of the disk. Can we have coexistence of finite-mass and infinite-mass blow-up?
- Sign-changing curvatures.
- Higher-order analogue.

# Muito obrigado pela sua atenção!

